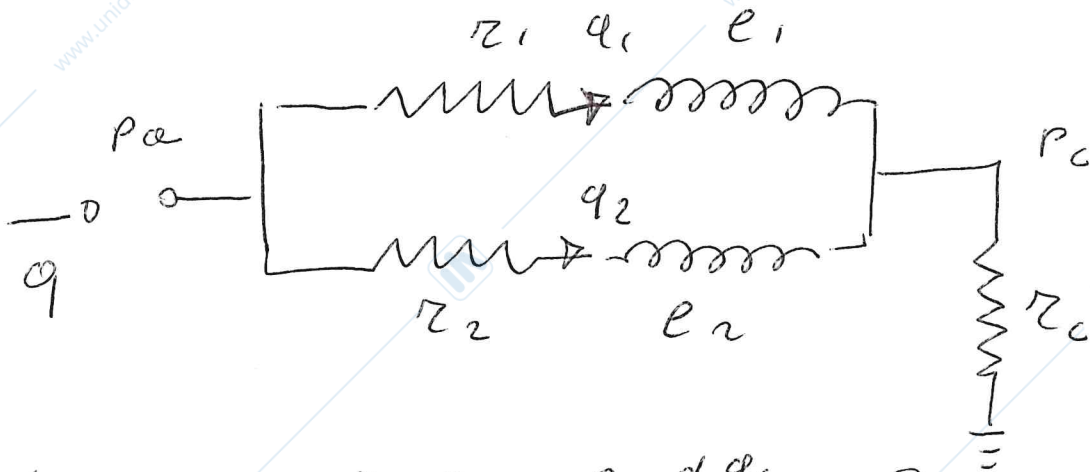


Esercizio

1



$$\left\{ \begin{array}{l} P_a - P_c = r_1 q_1 + l_1 \frac{dq_1}{dt} \\ P_a - P_c = r_2 q_2 + l_2 \frac{dq_2}{dt} \end{array} \right\} \text{eq. di stato}$$

$$P_c = r_c (q_1 + q_2) \quad \text{eq. ausiliaria}$$

$$\left\{ \begin{array}{l} l_1 \frac{dq_1}{dt} = -r_1 q_1 - r_c (q_1 + q_2) + P_a \\ l_2 \frac{dq_2}{dt} = -r_c (q_1 + q_2) - r_2 q_2 + P_a \end{array} \right.$$

$$\left\{ \begin{array}{l} \frac{dq_1}{dt} = -\frac{(r_1 + r_c)}{l_1} q_1 - \frac{r_c}{l_1} q_2 + \frac{P_a}{l_1} \\ \frac{dq_2}{dt} = -\frac{r_c}{l_2} q_1 - \frac{(r_2 + r_c)}{l_2} q_2 + \frac{P_a}{l_2} \end{array} \right.$$

$$A = \begin{bmatrix} -\frac{(r_1 + r_c)}{l_1} & -\frac{r_c}{l_1} \\ -\frac{r_c}{l_2} & -\frac{(r_2 + r_c)}{l_2} \end{bmatrix} \quad B = \begin{bmatrix} \frac{1}{l_1} \\ \frac{1}{l_2} \end{bmatrix}$$

Eq. uscita: $q = q_1 + q_2$

$$C = [1 \quad 1] \quad d = [\phi \quad \phi]$$

Funzione di trasferimento:

2

$$h(s) = C (sI - A)^{-1} B =$$

$$= [1 \quad 1] \frac{\text{adj}(sI - A)}{(s - \lambda_1)(s - \lambda_2)} \begin{bmatrix} \frac{1}{e_1} \\ \frac{1}{e_2} \end{bmatrix} =$$

$$= [1 \quad 1] \frac{\begin{bmatrix} s + \frac{r_2 + r_c}{e_2} & -\frac{r_c}{e_1} \\ -\frac{r_c}{e_2} & s + \frac{r_1 + r_c}{e_1} \end{bmatrix} \begin{bmatrix} \frac{1}{e_1} \\ \frac{1}{e_2} \end{bmatrix}}{(s - \lambda_1)(s - \lambda_2)}$$

$$= \frac{\begin{bmatrix} s + \frac{r_2 + r_c}{e_2} - \frac{r_c}{e_2} & s + \frac{r_1 + r_c}{e_1} - \frac{r_c}{e_1} \end{bmatrix} \begin{bmatrix} \frac{1}{e_1} \\ \frac{1}{e_2} \end{bmatrix}}{(s - \lambda_1)(s - \lambda_2)}$$

$$= \frac{e_2 s + r_2 + e_1 s + r_1}{e_1 e_2 (s - \lambda_1)(s - \lambda_2)} =$$

$$= \frac{(e_1 + e_2) s + r_1 + r_2}{e_1 e_2 (s - \lambda_1)(s - \lambda_2)}$$

funzione di trasferimento del circuito:

$$\frac{Pa(s)}{q(s)} = R_c + \frac{(r_1 + e_1 s)(r_2 + e_2 s)}{r_1 + r_2 + (e_1 + e_2)s} =$$

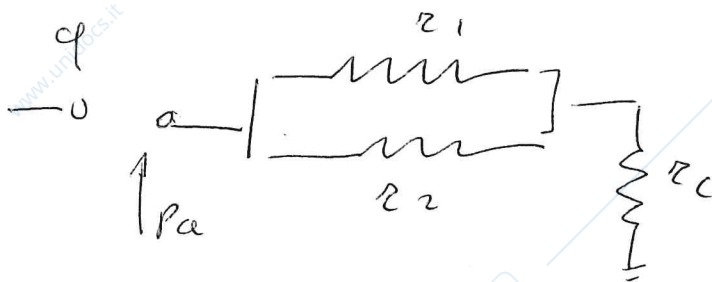
$$= \frac{R_c [r_1 + r_2 + (e_1 + e_2)s] + r_1 r_2 + r_1 e_2 s + r_2 e_1 s + e_1 e_2 s^2}{(e_1 + e_2)s + r_1 + r_2}$$

$$h(s) = \frac{q(s)}{Pa(s)} = \frac{(e_1 + e_2)s + r_1 + r_2}{e_1 e_2 s^2 + [r_1 e_2 + r_2 e_1 + R_c(e_1 + e_2)]s + r_1 r_2 + R_c(r_1 + r_2)}$$

Per ottenere una rettificata per $s = \phi$

$$h(\phi) = \frac{r_1 + r_2}{r_1 r_2 + R_c(r_1 + r_2)} = \frac{1}{\frac{r_1 r_2}{r_1 + r_2} + R_c}$$

che è esattamente (e' impedenze)



ammettenze

Che cosa dice il auto valore:

$$\begin{aligned}
 P(\lambda) &= \lambda^2 - T\lambda + \Delta = \\
 &= \lambda^2 + \left[\frac{r_1 + r_c}{e_1} + \frac{r_2 + r_c}{e_2} \right] \lambda + \\
 &\quad + \frac{r_1 + r_c}{e_1} \cdot \frac{r_2 + r_c}{e_2} - \frac{r_c^2}{e_1 e_2}
 \end{aligned}$$

$$T = - \frac{r_1 + r_c}{e_1} - \frac{r_2 + r_c}{e_2} < \phi$$

$$\Delta = \frac{r_1 r_2 + r_1 r_c + r_c r_2}{e_1 e_2} > \phi$$

$$h_{1,2} = \frac{T \pm \sqrt{T^2 - 4\Delta}}{2}$$

Si nota che $T^2 - 4\Delta =$

$$= \frac{r_1 + r_c}{e_1^2} + \frac{r_2 + r_c}{e_2^2} + 2 \frac{(r_1 + r_c)(r_2 + r_c)}{e_1 e_2} =$$

$$- 4 \left(\frac{r_1 + r_c}{e_1} \right) \left(\frac{r_2 + r_c}{e_2} \right) + \frac{r_c^2}{e_1 e_2}$$

$$= \left[\frac{r_1 + r_c}{e_1} - \frac{r_2 + r_c}{e_2} \right]^2 + \frac{r_c^2}{e_1 e_2} > \phi$$

quindi h_1 e h_2 sono reali

essendo $T < 0$

$\Delta > 0$

risultano due autovalore
reali negativi.



stabilità asintotica