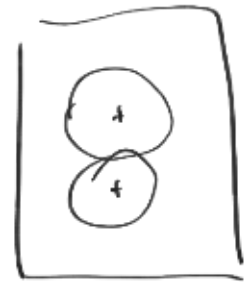
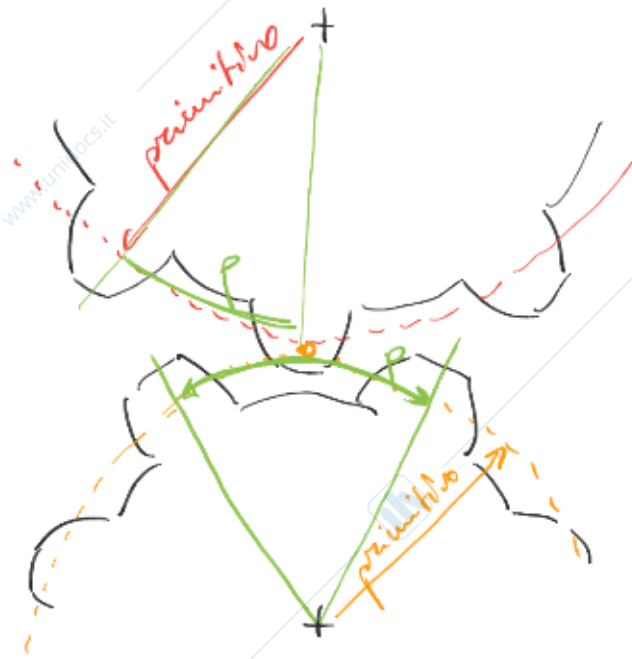
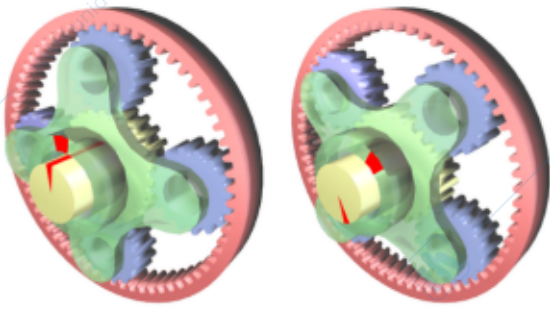


Ese 06 - Rotismo Epicicloidale



$z = \text{n}^\circ \text{ denti}$;

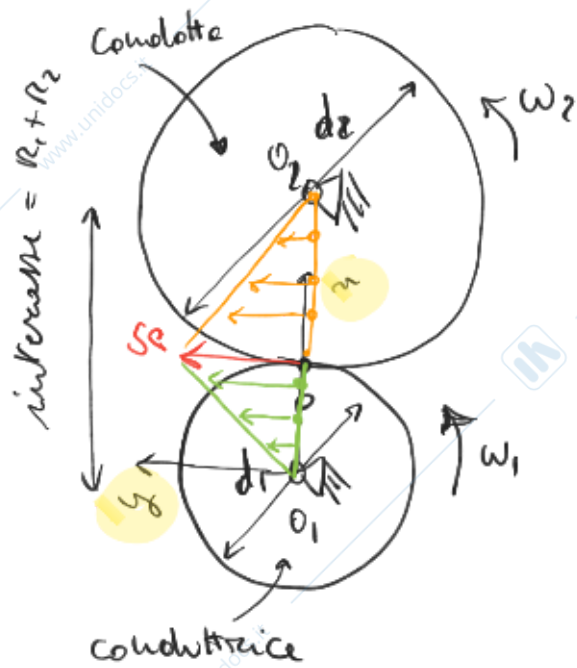
$d = \text{diametro primitivo}$

$$p = \frac{\pi d}{z}$$

↑
passo

$$m = \frac{d}{z} = \frac{p}{\pi}$$

↑
modulo



$$\begin{cases} \vec{v}_P = \omega_1 \vec{k} \wedge (P - O_1) \\ = \omega_1 \vec{k} \wedge R_1 \vec{x} \\ = \omega_1 R_1 \vec{y} \\ \vec{v}_P = \omega_2 \vec{k} \wedge (P - O_2) \\ = \omega_2 \vec{k} \wedge (-R_2 \vec{x}) \\ = -\omega_2 R_2 \vec{y} \end{cases}$$

$$\omega_1 R_1 = -\omega_2 R_2$$

$$\omega_2 = -\frac{R_1}{R_2} \omega_1$$

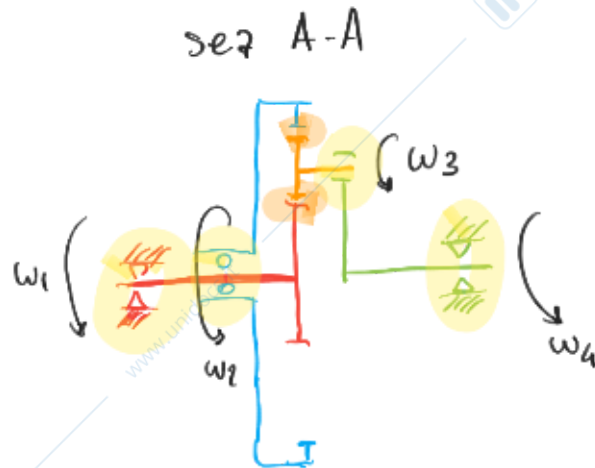
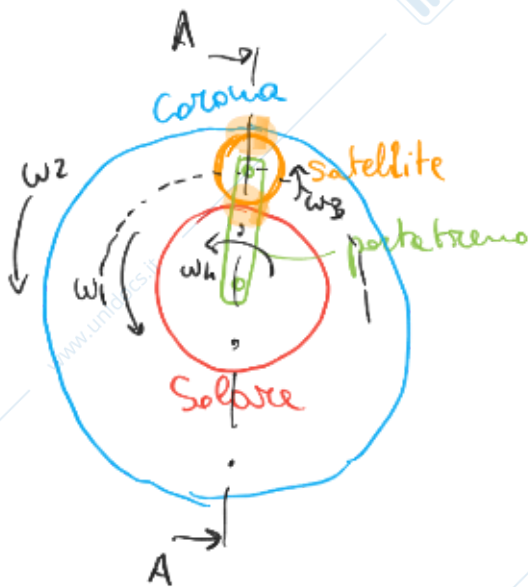
$$\omega_2 = \tau \omega_1$$

$$\tau = \frac{\omega_{uscita}}{\omega_{entrata}}$$

$$C = \frac{1}{\omega_1} = -\frac{1}{\omega_2} = -\frac{1}{\omega_3}$$

$$= -\frac{\frac{1}{\omega_1} z_1}{\frac{1}{\omega_2} z_2} = -\frac{z_1}{z_2}$$

$$m = \frac{d}{z}$$



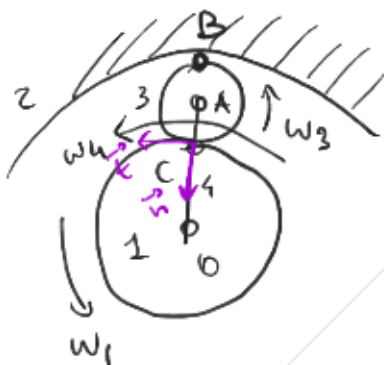
4 corpi → 12 gdl

4 cerniere → 8 pdl

2 rot senza strisciamento → 2 pdl
(2 contatti)

2 gdl residui

$\omega_2 = 0$ blocchiamo la corona



disco 3 → rotole senza strisciare rispetto al disco 2

B → $\vec{v}_B = 0$

B → CIR assoluta di (3)

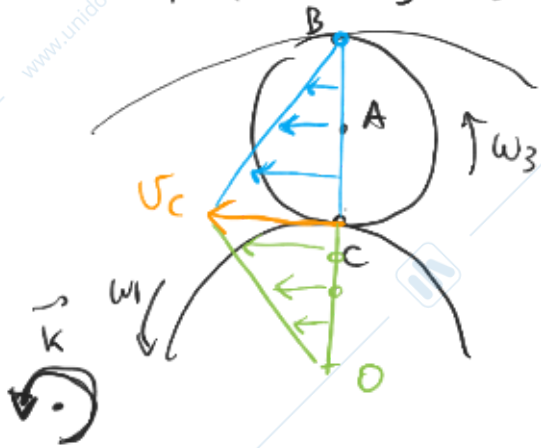
disco 1 ruota intorno a O

C → CIR moto relativo $\underline{[3-1]}$

$$\begin{cases} \vec{v}_C = \omega_1 \vec{k} \wedge (C-O) = \omega_1 \vec{k} \wedge (R_1 \vec{n}) = \omega_1 R_1 \vec{e} \\ \vec{v}_C = \omega_3 \vec{k} \wedge (C-B) = \omega_3 \vec{k} \wedge (2R_3 \vec{n}) = -\omega_3 2R_3 \vec{e} \end{cases}$$

$$\omega_1 R_1 = -\omega_3 2R_3 \rightarrow$$

$$\omega_3 = -\frac{R_1}{2R_3} \omega_1$$



$$\vec{v}_A = \frac{\vec{v}_C}{2} = \frac{\omega_1 R_1}{2} \vec{e}$$

Considerazioni geometriche

$$\vec{v}_A = \vec{v}_B + \omega_3 \vec{k} \wedge (A-B)$$

Rivalsa CIR

$$= -\frac{R_1}{2R_3} \omega_1 \vec{k} \wedge (R_3 \vec{h})$$

$$= -\frac{R_1 \omega_1}{2} (-\vec{e}) = \frac{R_1 \omega_1}{2} \vec{e}$$



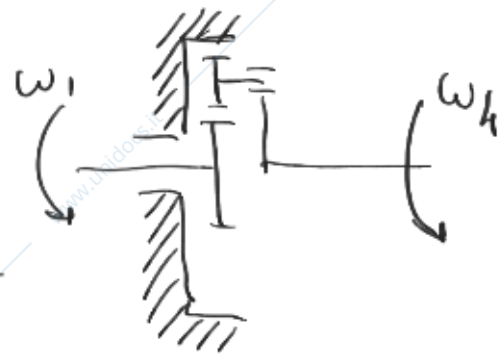
$$\vec{v}_A = \omega_4 \vec{k} \wedge (A-O)$$

$$= \omega_4 \vec{k} \wedge (-(R_1 + R_3) \vec{h})$$

$$= \omega_4 (R_1 + R_3) \vec{e} = \frac{R_1 \omega_1}{2} \vec{e}$$

$$\omega_4 = \frac{R_1}{2(R_1 + R_3)} \omega_1$$

$$\omega_4 = \tau_{41} \omega_1$$



$$\omega_1 = 0 \rightarrow \tau_{42} ?$$

$$1000 \rightarrow 6000 \text{ rpm}$$

$$v = 100 \text{ km/h} = \frac{100}{3.6} \approx 27 \text{ m/s}$$

$$R = 0,3 \text{ m}$$

$$\omega = \frac{v}{R} = 90 \text{ rad/s} \approx 860 \text{ rpm}$$



U → new . 1

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