

Testing and Certification (01NNKOQ)

Date of the examination: 28 January 2019

Student:

Surname _____

Name _____

Code _____

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Question 1

The electrical network of an industrial plant (nominal length 2 km) has to be monitored to estimate the current harmonic distortion. The current that flows through the network has a root mean square (rms) value in the range $(2 \div 50)$ A and a crest factor (peak to rms ratio) of 4.0. The available current sensors have a bandwidth of 2.5 kHz and an output voltage expressed as:

$$v_{\text{out}} = S \cdot i_{\text{IN}} + v_{\text{OFF}}$$

where $S = 0.1$ mV/A, 0.05% and $v_{\text{OFF}} = 0 \pm 2$ μ V.

The main requirements are:

- current resolution: 40 mA
- current uncertainty: 200 mA
- measuring nodes 100 m away from each other;
- samples acquired at each node sent to a central PC, which is located at one end of the plant, where an FFT algorithm is implemented that has to provide a frequency resolution of 50 Hz;
- data has to be updated every 2 s.

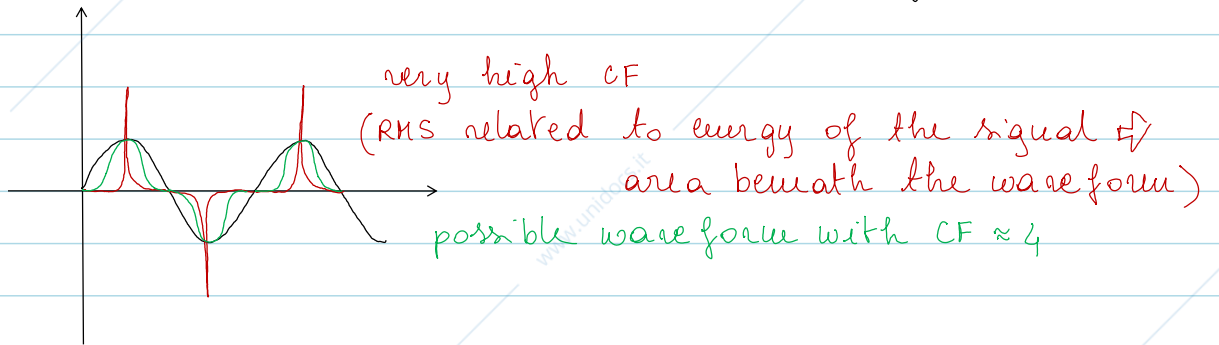
Design the data acquisition system providing details about conditioning circuitry, Analogue-to-Digital Converter and data-communication bus.

for the design problem multiple solutions exists
 ⇨ you have too meet the requirements

input quantity $I_{rms} = 2 \div 50 \text{ mA}$; $CF \triangleq \frac{I_{peak}}{I_{rms}} = 4$

for a sine wave as
 $V_{rms} = \frac{V_{peak}}{\sqrt{2}} \Rightarrow CF_{\text{sine wave}} = \sqrt{2} \approx 1.41$

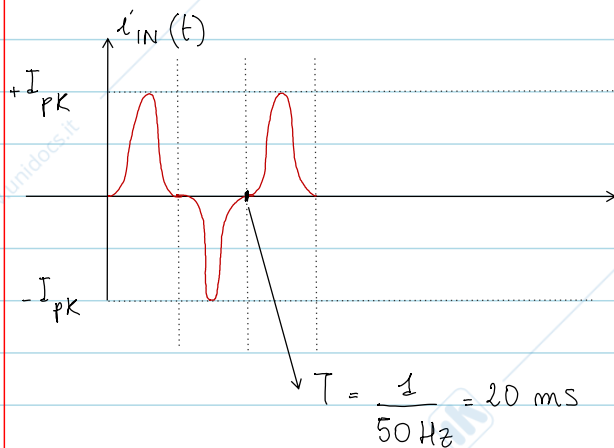
the crest factor is used to highlight the distortion of the signal



from the crest factor and RMS value it is possible to evaluate the peak value

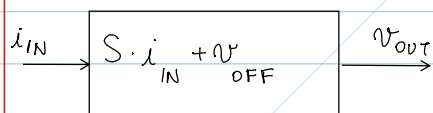
$I_{peak} = CF \cdot I_{rms} \Rightarrow I_{peak} (8 \div 200) \text{ A}$

the expected signal



we are working with an alternate signal the current i_{IN} at the input of the sensor has to be considered in the following range

$i_{IN} = (-200 \div 200) \text{ A}$



nominal estimation of the voltage output (nominal ⇨ $v_{OFF} = 0$)

$v_{OUT} = (-20 \div 20) \text{ mV}$

is it necessary to have something in between the output of the sensor and the input of the ADC?

⇨ consider the amplitude of the output of the sensor
 commitment that the signal at the input of ADC is
 matched as well as possible to the input range of the
 ADC ⇨ ADC with full range similar to $(-20 \div 20)$ mV

common ADC full ranges V_{FR} (both for unipolar/bipolar)

0.1 V

0.2 V

0.25 V

0.5 V

1 V

2 V

2.5 V

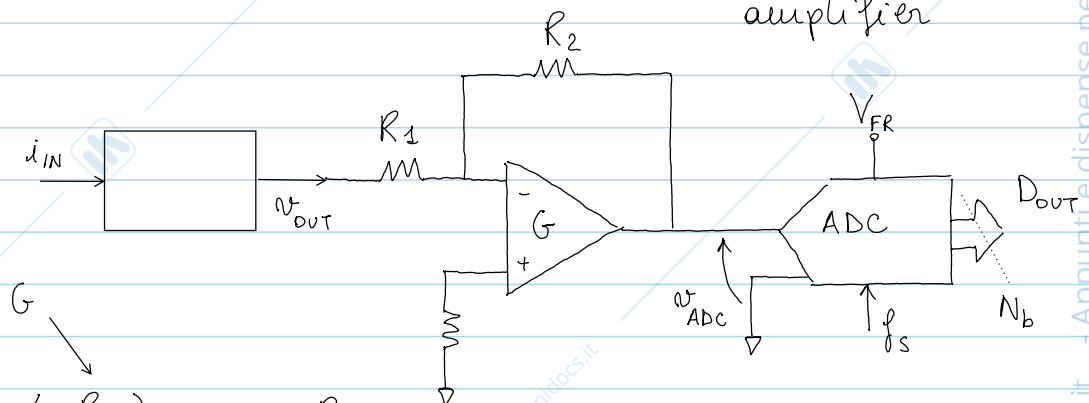
5 V

10 V

for this problem it could be fixed

$V_{FR} \cong 2$ V bipolar (full scale $V_{FS} \cong 1$ V)

commitment to put an amplifier between
 the sensor and ADC ⇨ inverting
 amplifier



$$v_{ADC} = v_{OUT} \cdot \left(-\frac{R_2}{R_1} \right) = -v_{OUT} \frac{R_2}{R_1}$$

$$|G_{MAX}| = \frac{V_{FS}}{\max\{v_{OUT}\}} = \frac{1 \text{ V}}{0.02 \text{ V}} = 50$$

the minus sign corresponds
 to a phase inversion
 as we are interested in
 amplitudes value it is not
 a problem

fixing the resistors R_1, R_2
 in order to obtain $|G| < |G_{MAX}|$

$$R_1 \cong 1 \text{ k}\Omega, R_2 \cong 47 \text{ k}\Omega \quad \Rightarrow \quad G = 47$$

for R_3 to minimize the offset at the output of the
 amplifier $R_3 \cong R_1 \parallel R_2$

fixing the sampling rate of the ADC

⇒ maximum frequency content of the signal ⇒ sensor bandwidth

$$f_{\text{MAX}} \approx \text{BW} = 2.5 \text{ KHz}$$

as $f_s \geq 2.5 f_{\text{MAX}} \Rightarrow f_s \triangleq 4 f_{\text{MAX}} = 10 \text{ K} \frac{\text{Sa}}{\text{s}}$ large f_s has consequences

(Nyquist)

estimation of v_{ADC} range

$$v_{\text{ADC}} = v_{\text{OUT}} \cdot |G| = v_{\text{OUT}} \cdot 47 = (-0.94 \div 0.94) \text{ V}$$

estimation of $N_b \Rightarrow$ we need to fix V_q

$$v_{\text{ADC}} = (S \cdot i_{\text{IN}} + v_{\text{OFF}})$$

$$\Delta v_{\text{ADC}} = \left| \frac{\partial v_{\text{ADC}}}{\partial i_{\text{IN}}} \right| = \Delta i_{\text{IN}} \xrightarrow{\text{design requirement}} \Delta i_{\text{IN}} = 0.04 \text{ A}$$

current resolution

$$\Delta v_{\text{ADC}} = S G \Delta i_{\text{IN}} \approx 0.19 \text{ mV}$$

so the ADC has to assure a resolution $V_q \leq \Delta v_{\text{ADC}}$

$$\text{as } V_q = \frac{V_{\text{FR}}}{2^{N_b}} \leq \Delta v_{\text{ADC}} \Rightarrow 2^{N_b} \geq \frac{V_{\text{FR}}}{\Delta v_{\text{ADC}}} \approx 10638 \text{ levels}$$

$$N_b = \left\lceil \log_2 2^{N_b} \right\rceil = 14$$

$$\text{I/O relationship } D_{\text{OUT}} = \frac{v_{\text{ADC}}}{V_q} = \frac{S \cdot i_{\text{IN}} + v_{\text{OFF}}}{V_q} \cdot \frac{R_2}{R_1}$$

$$\max \{ D_{\text{OUT}} \} = \frac{\max \{ v_{\text{ADC}} \}}{V_q} = \frac{0.94}{2/2^{14}} \approx 7700 \text{ LSB}$$

comparing to the 14 bit bipolar ADC range $(-2^{13} \div 2^{13} - 1)$ LSB which corresponds to $(-8096 \div 8095)$ LSB

uncertainty requirements \Leftrightarrow calibration function

$$i_{IN} = \frac{1}{S} D_{OUT} \cdot V_q \cdot \frac{R_1}{R_2} - v_{OFF} \quad \text{this represents the measuring model}$$

worst case approach for the design problem as requirements on the input must be assured

$$\delta i_{IN} = \left| \frac{\partial i_{IN}}{\partial S} \right| \delta S + \left| \frac{\partial i_{IN}}{\partial D_{OUT}} \right| \delta D_{OUT} + \left| \frac{\partial i_{IN}}{\partial R_1} \right| \delta R_1 + \left| \frac{\partial i_{IN}}{\partial R_2} \right| \delta R_2 + \left| \frac{\partial i_{IN}}{\partial v_{OFF}} \right| \delta v_{OFF}$$

sensitivity coeff. can be computed

δS , δv_{OFF} are known values

design requirements $\Leftrightarrow \delta i_{IN} \leq 0,2 \text{ A}$

computing $\left| \frac{\partial i_{IN}}{\partial S} \right| \delta S$ and $\left| \frac{\partial i_{IN}}{\partial v_{OFF}} \right| \delta v_{OFF}$ and take into

account that $\delta i_{IN} \leq 0,2 \text{ A}$ we have a residual uncertainty to split between $\left| \frac{\partial i_{IN}}{\partial R_1} \right| \delta R_1$, $\left| \frac{\partial i_{IN}}{\partial R_2} \right| \delta R_2$, $\left| \frac{\partial i_{IN}}{\partial D_{OUT}} \right| \delta D_{OUT}$

as the sens. coeff. are known

$$\left| \frac{\partial i_{IN}}{\partial D_{OUT}} \right| = \frac{V_q}{S} \cdot \frac{R_1}{R_2} = 0,026 \frac{\text{A}}{\text{LSB}} \triangleq c1$$

$$\left| \frac{\partial i_{IN}}{\partial R_1} \right| = \frac{\max\{D_{OUT}\} V_q}{S R_2} = 0,2 \frac{\text{A}}{\Omega} \triangleq c2$$

$$\left| \frac{\partial i_{IN}}{\partial R_2} \right| = \frac{\max\{D_{OUT}\} V_q R_1}{S R_2} = 4,3 \cdot 10^{-3} \frac{\text{A}}{\Omega} \triangleq c3$$

$$\left| \frac{\partial i_{IN}}{\partial S} \right| = \frac{\max\{D_{OUT}\} V_q}{S^2} \cdot \frac{R_1}{R_2} = 2 \cdot 10^6 \frac{\text{A}}{\text{V/A}} \triangleq c4$$

$$\left| \frac{\partial i_{IN}}{\partial v_{OFF}} \right| = \frac{1}{S} = 1 \cdot 10^4 \text{ A/V} \triangleq c5$$

$$\delta i_{IN} = c_1 \delta D_{OUT} + c_2 \delta R_1 + c_3 \delta R_2 + c_4 \delta S + c_5 \delta v_{OFF} \leq 0.2 \text{ A}$$

$$c_4 \delta S = c_4 \frac{0.05}{100} \cdot S = 0.1 \text{ A}$$

Known

design requirement

$$c_5 \delta v_{OFF} = c_5 \cdot \frac{1}{S} = 0.02 \text{ A}$$

so it must be $c_1 \delta D_{OUT} + c_2 \delta R_1 + c_3 \delta R_2 \leq (0.2 \text{ A} - 0.12 \text{ A}) = 80 \text{ mA}$

by considering $c_1 \delta D_{OUT} + c_2 \delta R_1 + c_3 \delta R_2 = 80 \text{ mA}$

so now we must assign values for $c_1 \delta D_{OUT}$, $c_2 \delta R_1$, $c_3 \delta R_2$ as the ADC is normally the largest uncertainty contribution
 $0.5 \cdot 80 \text{ mA} = c_1 \delta D_{OUT}$, $0.25 \cdot 80 \text{ mA} = c_2 \delta R_1 = c_3 \delta R_2$

$$\delta D_{OUT} = \frac{c_1 \delta D_{OUT}}{c_1} = \frac{0.5 \cdot 80 \text{ mA}}{c_1} \approx 1.5 \text{ LSB}$$

$$\delta R_1 = \frac{0.02 \text{ A}}{c_2} = 0.1 \Omega \Rightarrow \epsilon_{R_1\%} = 0.01\%$$

$$\delta R_2 = \frac{0.02 \text{ A}}{c_3} \approx 4.7 \Omega \Rightarrow \epsilon_{R_2\%} = 0.01\%$$

different abs. uncertainty as it depends to the resistor value

same relative uncertainty as the same residual uncertainty was assigned to the two resistors of the amplifier

for the ADC $\Rightarrow \delta D_{OUT} \leq 1.5 \text{ LSB}$

it's possible to actuate zero/gain compensations

implementation of the BUS

\Rightarrow how many bits each node has to transmit to the central unit? \Rightarrow transmission rate?

$$\text{starting with the number of nodes } \Rightarrow N_{\text{NODES}} = \frac{L}{\Delta L} = \frac{2 \text{ Km}}{0.1 \text{ Km}} = 20$$

processing of the unit \Rightarrow FFT algorithm resolution $\Delta f = 50 \text{ Hz}$
 the frequency resolution is the reciprocal of the acquisition interval

each mode must acquire samples of the current signal for
 $\Delta t = \frac{1}{\Delta f} = 20 \text{ ms}$

number of samples collected at each mode

$$N_{\text{samples}} = f_s \cdot \Delta t = 200 \text{ Sa}$$

converting samples \Rightarrow bits

$$N_{\text{bit}} = N_{\text{samples}} \cdot N_b = 200 \cdot 14 = 2800 \text{ bit} \quad (\text{no protocol overhead})$$

$$\text{transmission rate} \quad TR = \frac{N_{\text{modes}} \cdot N_{\text{bit}}}{\text{update rate}} = \frac{20 \cdot 2800}{2} = 28 \text{ Kbit/s}$$

\downarrow sys requirem.

$$f_s (\text{ADC}) \uparrow, N_b (\text{ADC resolution}) \Rightarrow TR \uparrow$$

$$\text{minimize } f_s, N_b \Rightarrow \text{minimize } TR$$

$$\text{as } TR < 31.25 \text{ Kbit/s} \Rightarrow \begin{cases} \text{Fieldbus} \\ \text{Profibus PA} \end{cases}$$

possible choice: Fieldbus NB max 1 Km, max 10 modes

\Rightarrow 2 sections (10 modes / section of 1 Km)

1 repeater